



(Knowledge for Development)

KIBABII UNIVERSITY
UNIVERSITY EXAMINATIONS
2016/2017 ACADEMIC YEAR
SECONDYEAR FIRST SEMESTER
SPECIAL/ SUPPLEMENTARY EXAMINATION
FOR THE DEGREE OF BACHELOR OF SCIENCE
MATHEMATICS

COURSE CODE: MAT 212

COURSE TITLE: LINEAR ALGEBRA

DATE: 18/09/17

TIME: 3 PM -5 PM

INSTRUCTIONS TO CANDIDATES

Answer Question One and Any other TWO Questions

TIME: 2 Hours

This Paper Consists of 5 Printed Pages. Please Turn Over.

QUESTION ONE (30 MKS)

(a) (i) Define subspace of vector spaces and a basis of a vector space (2mks)

(ii) Show that $V_4 \equiv$ the set consisting of all real valued continuous functions defined on the entire real line is a vector space. (5mks)

(b) Let $W = \{(x_1, x_1 + x_3, x_3) : x_1 \text{ and } x_3 \text{ are real numbers}\}$. Show that W is a subspace of R^3 . (4mks)

(c) Solve the system below using Gaussian Elimination with back-substitution. (4mks)

$$x - 2y + 3z = 9$$

$$-x + 3y = -4$$

$$2x - 5y + 5z = 17$$

(d) (i) Show that the set $S = \{(1,1), (1,-1)\}$ is a basis for R^2 (4mks)

(ii) Determine whether the set of vectors below is linearly independent or dependent (5mks)

$$S = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$$

(e) (i) Find the kernel of the linear transformation $T: R^2 \rightarrow R^3$ represented by $T(x_1, x_2) = (x_1 - 2x_2, 0, -x_1)$. (3mks)

(ii) Show that the linear transformation $T: R^2 \rightarrow R^2$ represented by the matrix

$$A = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

Has the property that it rotates every vector in R^2 counter clockwise about the origin through angle θ (3 mks)

QUESTION TWO (30 MKS)

(a) Use Gauss – Jordan elimination to solve the system

$$\begin{aligned}x+2y-2z &= -3 \\w+2x-y &= 2 \\2w+4x+y-3z &= -2 \\w-4x-7y-z &= -19\end{aligned}\tag{6mks}$$

(b) Write the vector $w = (1, 1, 1)$ as a linear combination of vectors in the set S , where

$$S = \{(1, 2, 3), (0, 1, 2), (-1, 0, 1)\}\tag{7 mks}$$

2(c) Proof that $S = v_1, \dots, v_n$ form a basis of vector space V if and only if every $v \in V$ can be written uniquely as $v = \alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n$: the coefficients $\alpha_1, \alpha_2, \dots, \alpha_n$ are uniquely determine by the vector v . (4mks)

2(d) Proof that if W_1 and W_2 are subspaces of V then so is $W_1 \cap W_2$. (3 mks)

QUESTION THREE (30 MKS)

(a) Let U and W be subspace of a vector space V . Show that:

- (i) $U + W$ is a subspace of V (3mks)
- (ii) U and W are contained in $U + W$ (2mks)
- (iii) $U + W$ is the smallest subspace containing U and W ; that is $U + W = \text{span}(U, W)$. (2mks)
- (iv) $W + W = W$ (2 mks)

(b) Solve the system of linear equation below

$$\begin{aligned}x - y + 3z &= 0 \\2x + y + 3z &= 0\end{aligned}\tag{5mks}$$

(c) Proof that:

- (i) If A is an invertible matrix, then its inverse is unique. (3mks)
- (ii) If A, B and C are invertible matrix and $AC = BC$, then $A = B$ (3mks)

QUESTION FOUR (30 MKS)

- (a) Determine whether the set of vectors S in R^3 is linearly independent or linearly dependent. Where, $S = \{(1,2,3), (0,1,2), (-2,0,1)\}$ (6 mks)
- (b) Find the inverse of the matrix below (6 mks)

$$A = \begin{pmatrix} 1 & -1 & 0 \\ 1 & 0 & -1 \\ -6 & 2 & 3 \end{pmatrix}$$

- (c) Proof that if $S = \{v_1, v_2, \dots, v_k\}$ is a set of vectors in a vector space V , then $\text{span}(S)$ is a subspace of V . (4 mks)
- (d) Proof that a set $S = \{v_1, v_2, \dots, v_n\}$, $n \geq 2$, is linearly dependent if and only if at least one of the vectors v_j can be written as a linear combination of the other vectors in S . (4mks)

QUESTION FIVE (30 MKS)

- (a) Solve the system (7mks)
- $$\begin{aligned} u - v + 2w &= 4 \\ u + w &= 6 \\ 2u + 3v + 5w &= 4 \\ 3u + 2v - w &= 1 \end{aligned}$$
- (b) Proof that if the vectors v_1, v_2, \dots, v_n , w span V and that w is a linear combination of v_1, v_2, \dots, v_n , then v_1, v_2, \dots, v_n span V . (6mks)
- (c) Find the kernel of the linear transformation, $T: R^3 \rightarrow R^2$ defined by $T(x) = A(x)$, where

$$A = \begin{pmatrix} 1 & -1 & -2 \\ -1 & 2 & 3 \end{pmatrix} \quad (7 \text{ mks})$$